

Structured stochastic processes and functional data analysis for the assessment of motor learning in normal and pathological subjects

(Postdoctoral research submitted to FAPESP)

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II NeuroMat Workshop: New Frontiers in Neuromathematics

November 2016

Recent results [A. Duarte, R. Fraiman, A. Galves, G. Ost and C.D. Vargas, arXiv:1602.00579]

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Stochastic process driven by context tree model

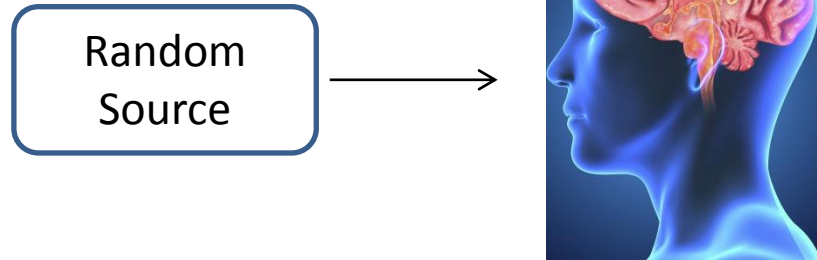
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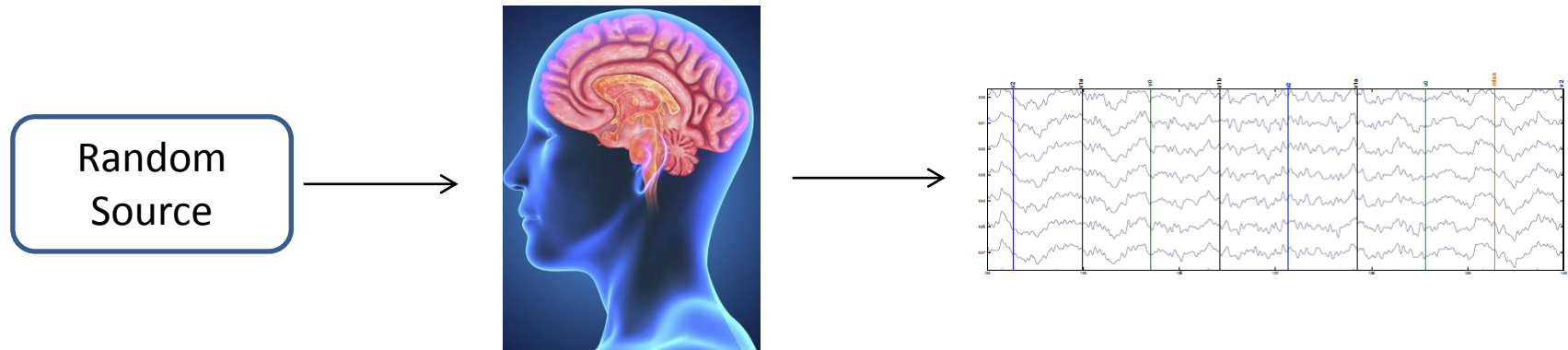
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- Allows a design, modeling and analysis of neurophysiological experiments with structured stimuli

Retrieving a context tree form EEG data

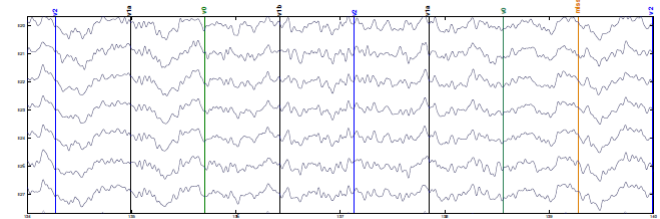
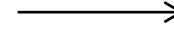
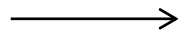


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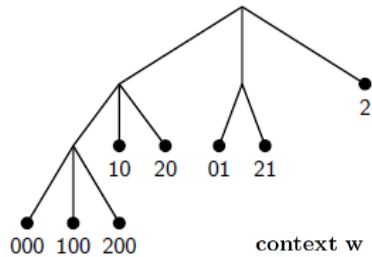
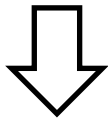


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Random Source



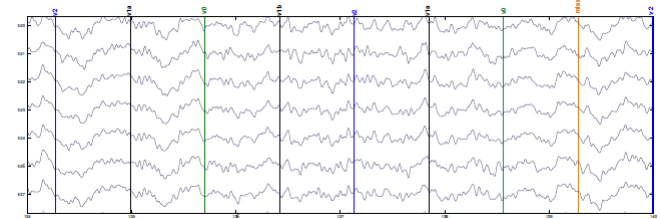
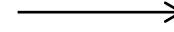
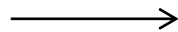
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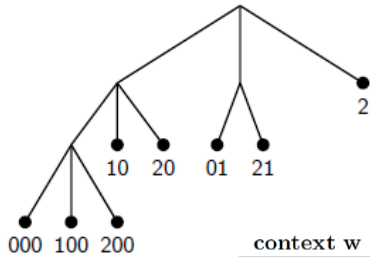
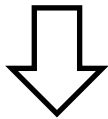
context w	$p(1 w)$	$p(2 w)$
2	$1 - \epsilon$	0
21	0	0
20	0	0
10	$1 - \epsilon$	0
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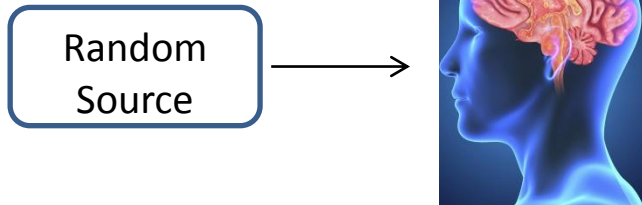
- $(X_1, Y_1), \dots, (X_n, Y_n)$
- New statistical model selection procedure for FD
- The brain effectively identifies the context tree characterizing the source.

Can such finding be corroborated in behavioral responses, specifically in execution of movements?

Images taken from

https://www.lvhn.org/for_referring_physicians/better_medicine/rehabilitation/neuromuscular_rehabilitation_technology_helps_patients_increase_motor_control; <http://neuromat.numec.prp.usp.br/pt-br/newsletter-31>; <https://lehacker.com/brain-facts-revealing/>

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Rehabilitation of patients



Goalkeeper Game



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 - for some l ,
 - any $m \geq l$, ($l, m \in \mathbb{Z}$)
 - and any finite string $x_{n-m}^{n-1} = (x_{n-m}, \dots, x_{n-1}) \in A^m$,

$$\begin{aligned} P(X_n = a | X_{n-m}^{n-1} = x_{n-m}^{n-1}) &= P(X_n = a | X_{n-l}^{n-1} = x_{n-l}^{n-1}) \\ &= P(X_n = a | c(x_{n-l}^{n-1})) \text{ for all } a \in A. \end{aligned}$$

- $c : A^l \rightarrow \mathcal{C} = \{c_1, \dots, c_m\}$: mapping assigning to each past string a corresponding class in a partition of the space of relevant pasts.

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 - Y_1, Y_2, \dots are independent variables conditionally to the sequence $(X_n)_{n \in \mathbb{Z}}$

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Stochastic processes driven by context tree model is an outstanding example of SPDSMC

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FD representing trajectory

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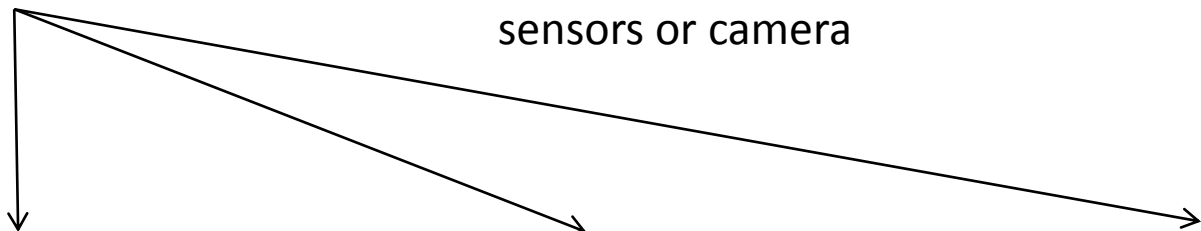
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$Y_n \in Y = \{0,1,2\} \times \{G, B\}$

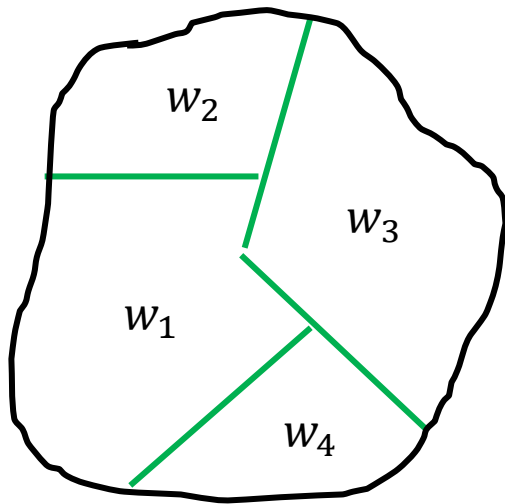


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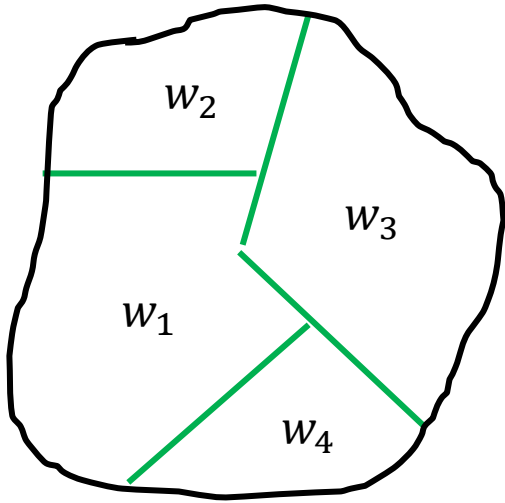
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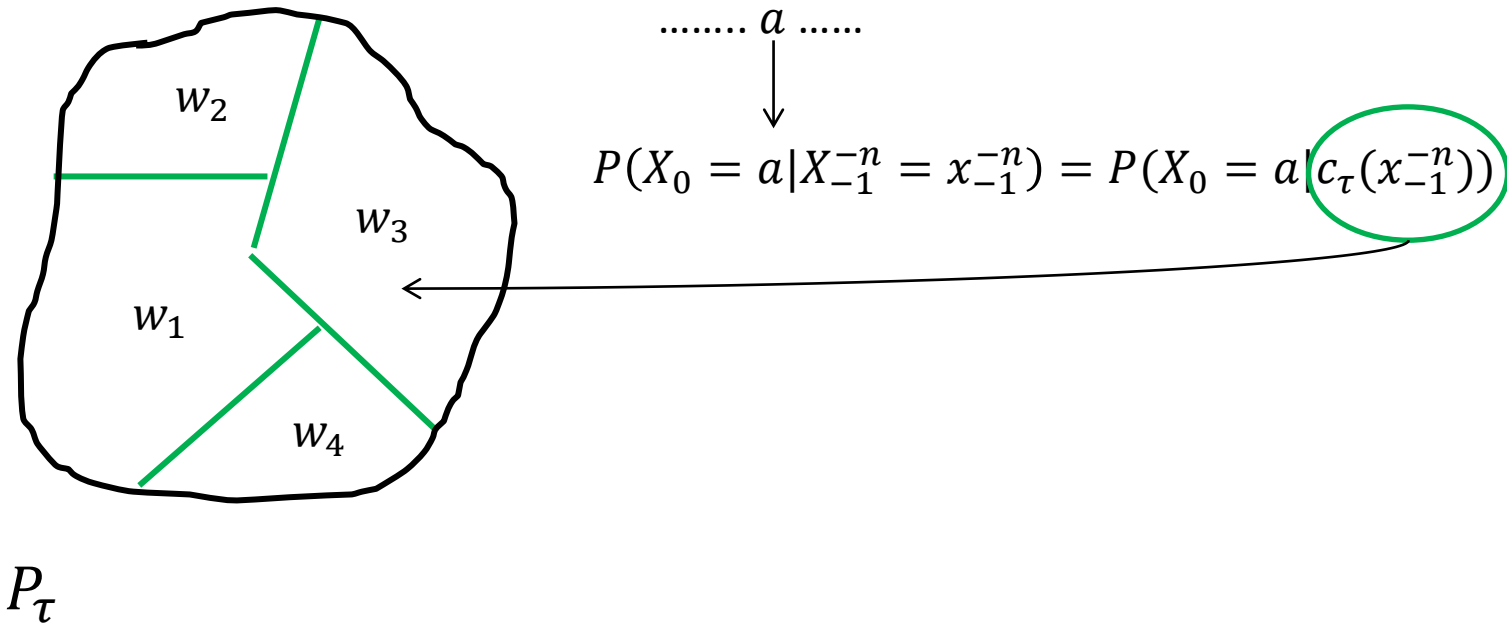


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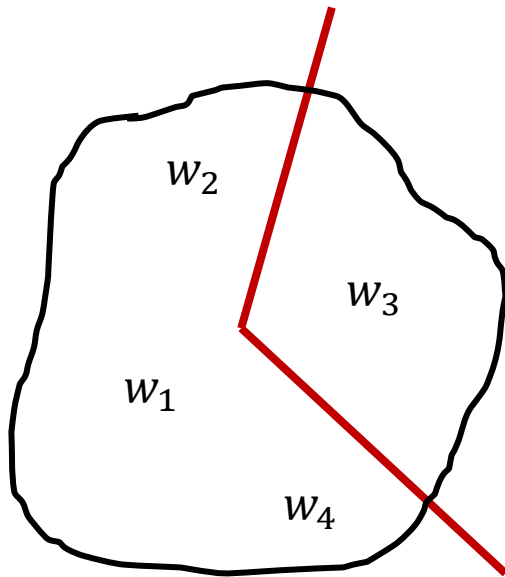
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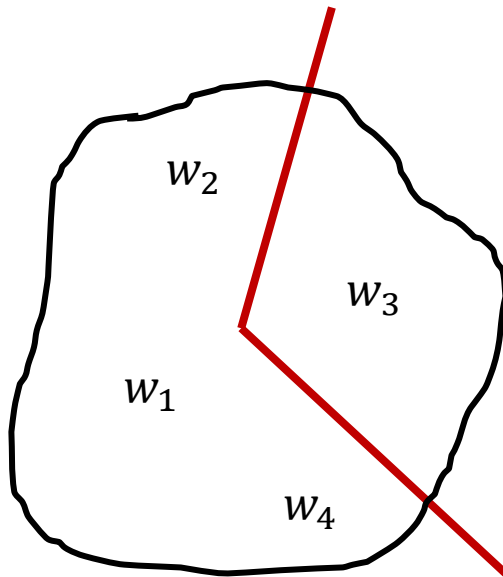


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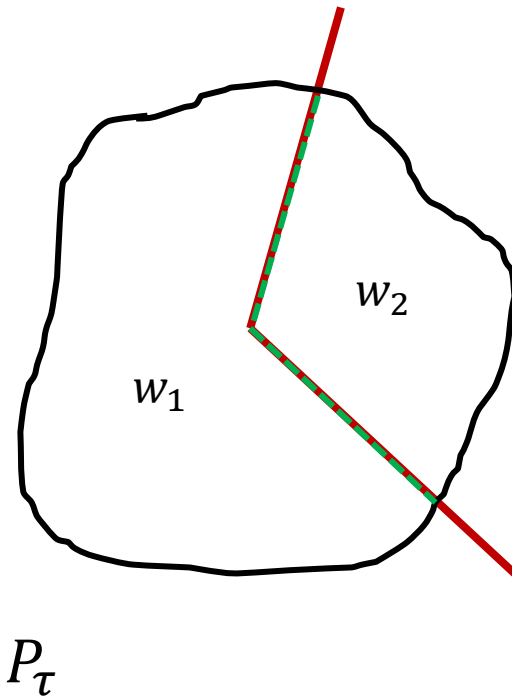
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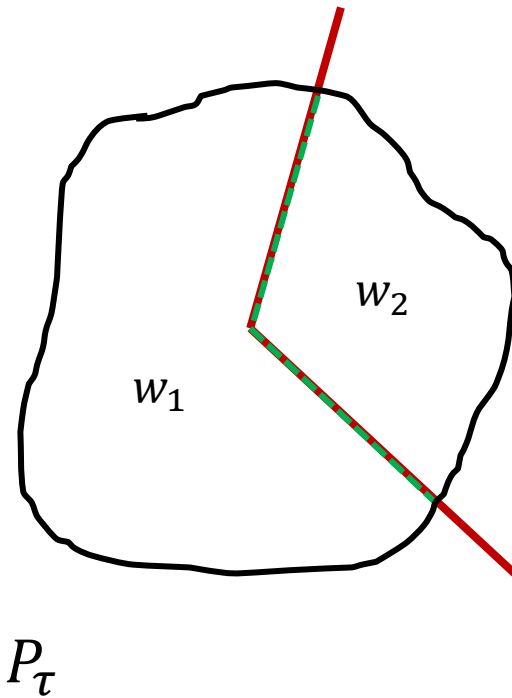
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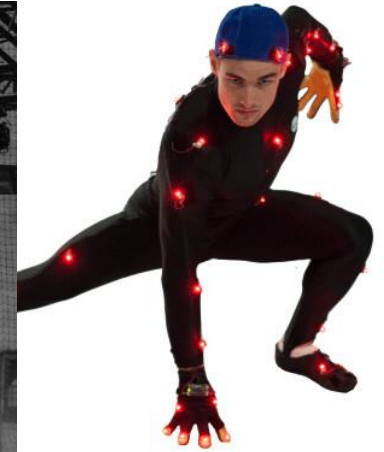
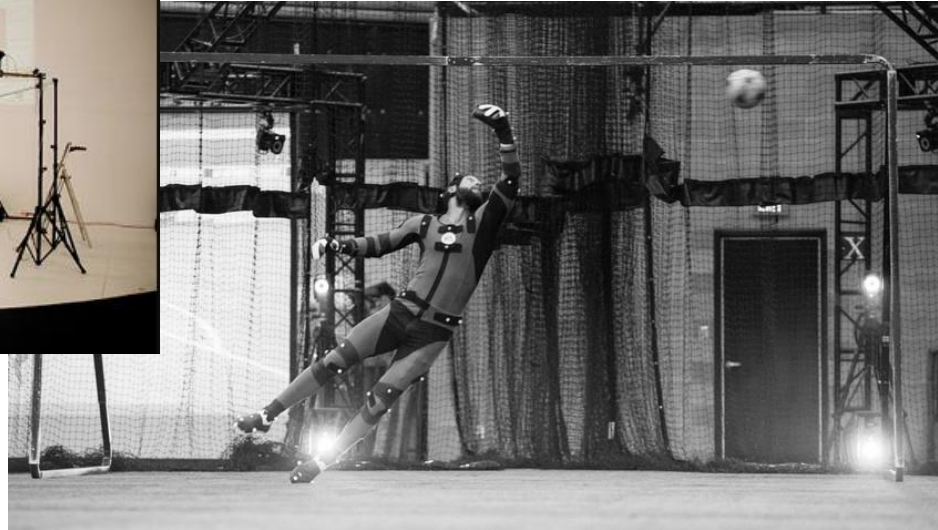
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- How to quantify and control the complexity of the statistical pattern?

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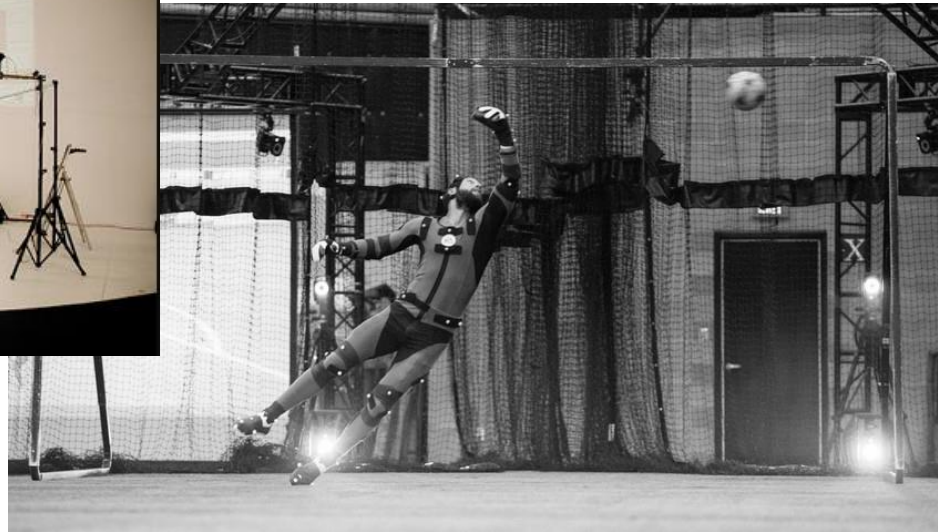
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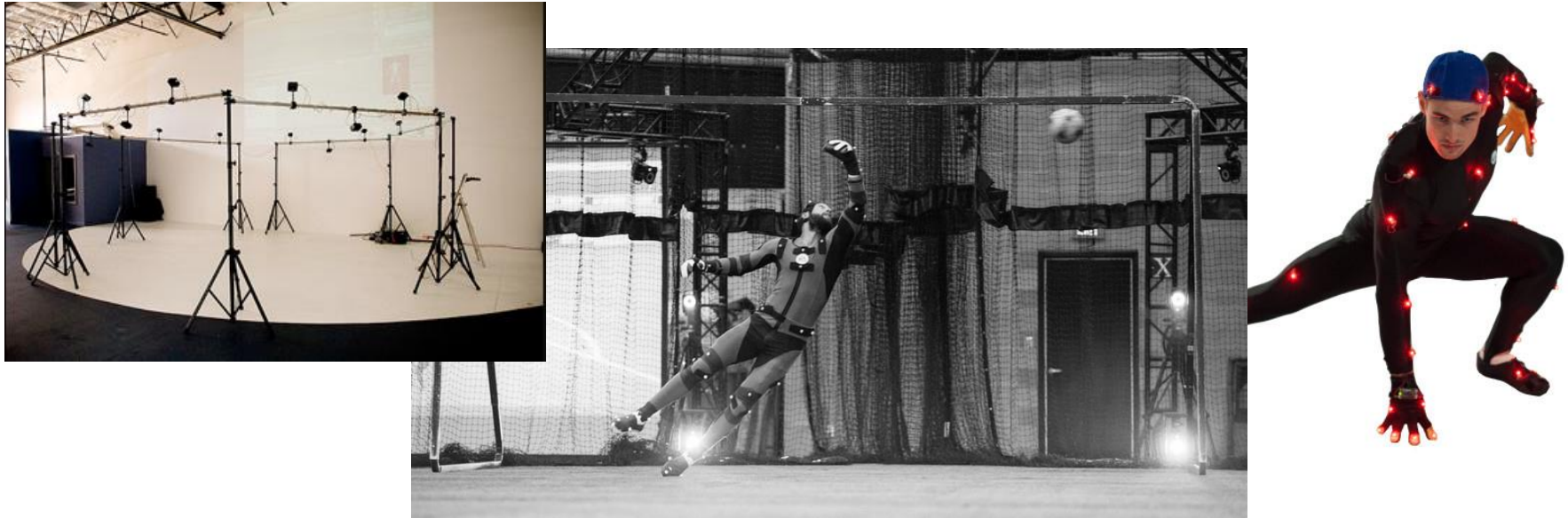
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- Pattern recognition techniques and machine learning algorithms
 - Computer vision techniques
 - **Gesture representation** and recognition $\longrightarrow Y_n$
 - Tracking algorithms

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A consistent model selection procedure

[A. Duarte, R. Fraiman, A. Galves, G. Ost and C.D. Vargas, arXiv:1602.00579]

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Functional test that focus on particular parameters:

mean functions

covariance operators

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- Functional cluster analysis
- Dissimilarity measures between functional populations
- Functional shape analysis
- Functional time series methods

Thank you